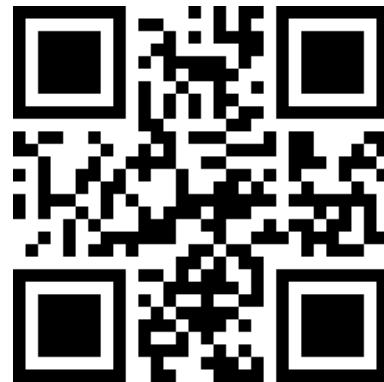


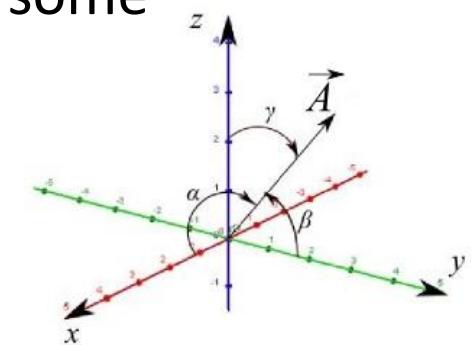
# NaviCode

Symbology Designed for AGV Navigation



# Essential Aspects for Navigation

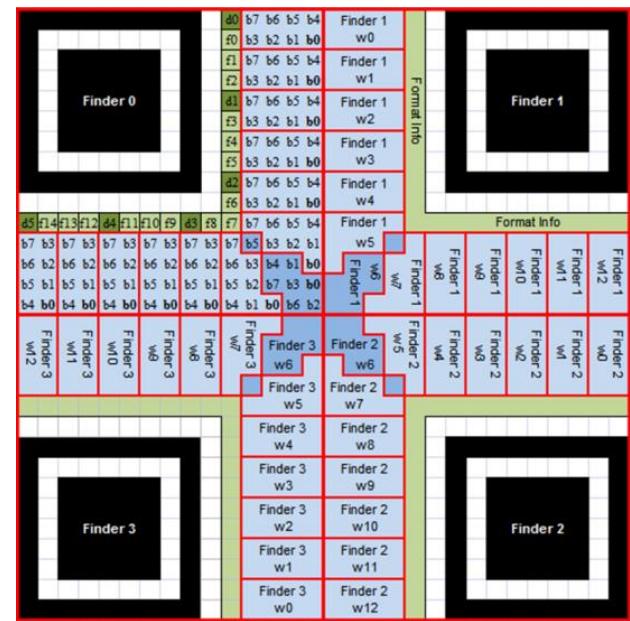
- For navigation, 3D gesture info is necessary for motion control
  - Including 3 angles & a reference point (ref. Appendix A.)
- To achieve effective navigation while moving, some measuring quality to be ensured:
  - Precision
  - Speed
  - Robustness
- *NaviCode* provides a specifically designed symbology structure to make sure these navigation info can be retrieved more fast, accurately, and reliably than other counterparts.



# Features

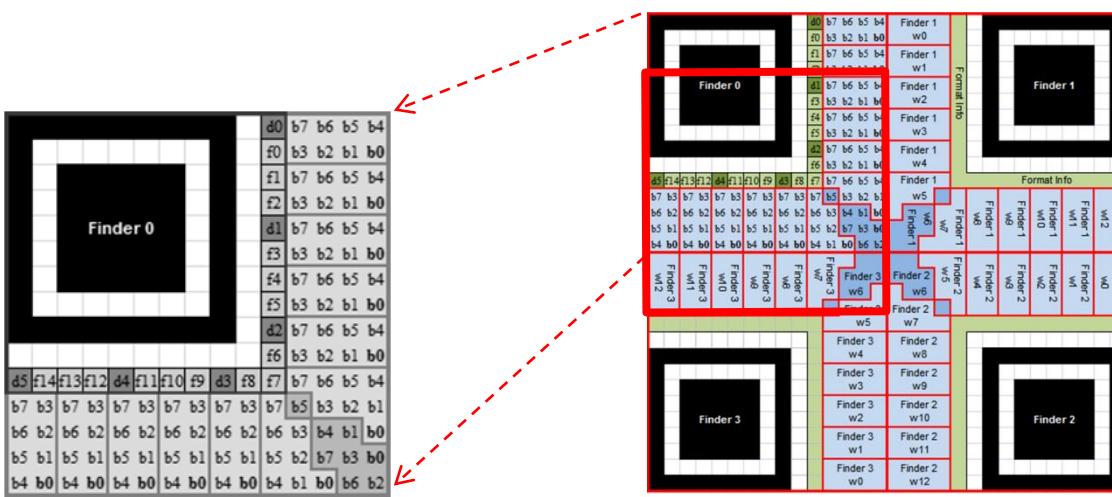
To support effective navigation, **NaviCode** features :

- Fully symmetric symbology
- High error-correction capability
- 4-bulleye symbology
- Better bulleye-kernel width ratio
- Data security



# Fully Symmetric Symbology

- **Fast localization:** one eye registered, all eyes registered;
- Inter-block symmetry & Intra-block symmetry, for **fast data/format info retrieval**;
- 4 fully symmetric data module areas are designed to **accelerate decoding process** and **enhance robustness**;
- No any existing 2D symbology are fully symmetric.



# High Error-Correction Capability

- Up to **44-byte data** for navigation info;
- Data region is protected by **Reed-Solomon codes w/ ECC capability up to 46%**; format info by BCH(15,5) code;
- Flat symbol sizes w/ 8 data capacity options.

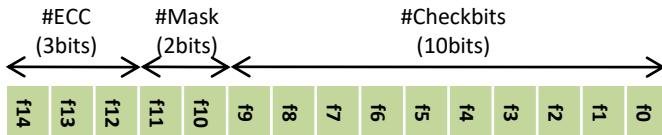


Figure. BCH code(15,5) for #ECC/#Mask information

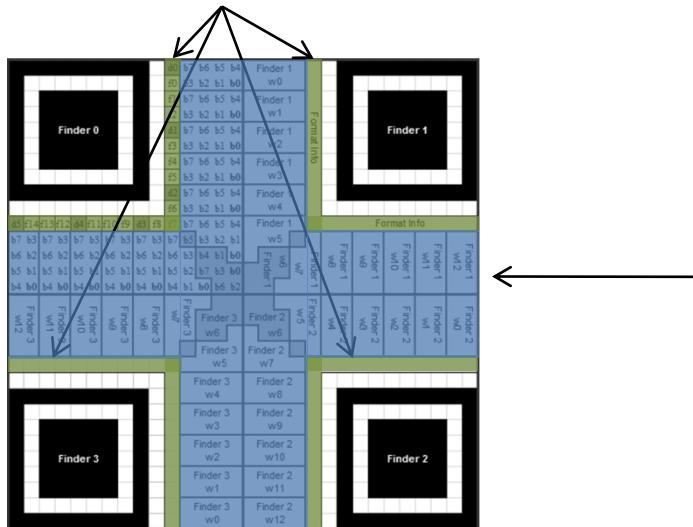


Table. Reed-Solomon Error Correction Levels and Data Capacity

ECC Level	#Data (bytes)	#Ecc (bytes)	#Codeword (bytes)	RS (c, k, r)	Max Correction
0	44	8	52	(52,44, 4)	8%
1	40	12	52	(52,40, 6)	12%
2	36	16	52	(52,36, 8)	15%
3	32	20	52	(52,32,10)	19%
4	26	26	52	(52,26,13)	25%
5	20	32	52	(52,20,16)	31%
6	12	40	52	(52,12,20)	38%
7	4	48	52	(52, 4,24)	46%

# 4-Bulleye Symbology

- 4 uniquely identified bulleyes to provide **higher precision** of navigation info, specifically, *NaviCode symbol's position & camera's inclination angles & orientation angle*;
- **Robust** to loss of part of symbols & to corrupted eyes;

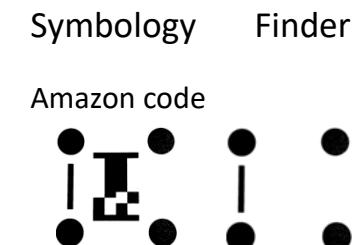
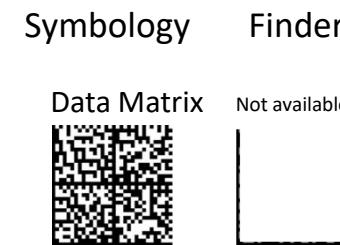
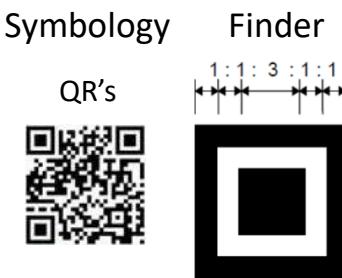
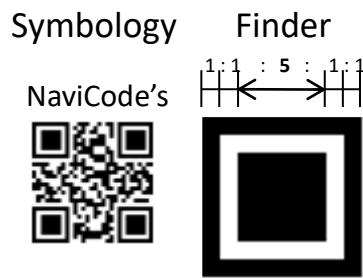
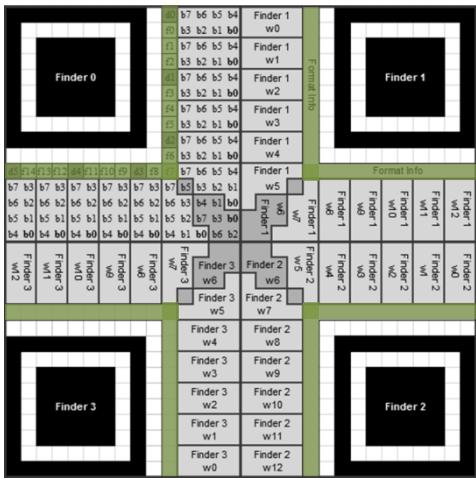


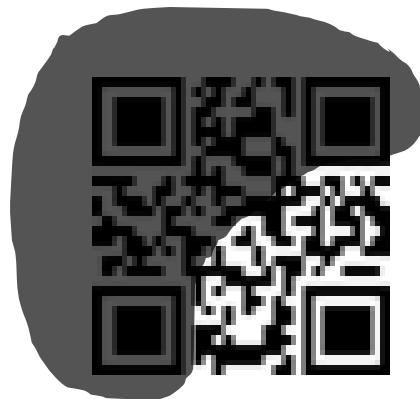
Figure. Popular symbologies for navigation applications

# Data Security

- Incompatible w/ any existing 2D codes;
- **Higher error correction ability** to enhance robustness  
(as high as~46%, comparing to that of QR/DM ~30% and of Amazon code ~0%);
- 4 copies of ECC protected format info to support, in worst case, single bull eye decoding;
- **Data encryption** with user-specified keys.



Four copies of format info



NaviCode decodable worse-case



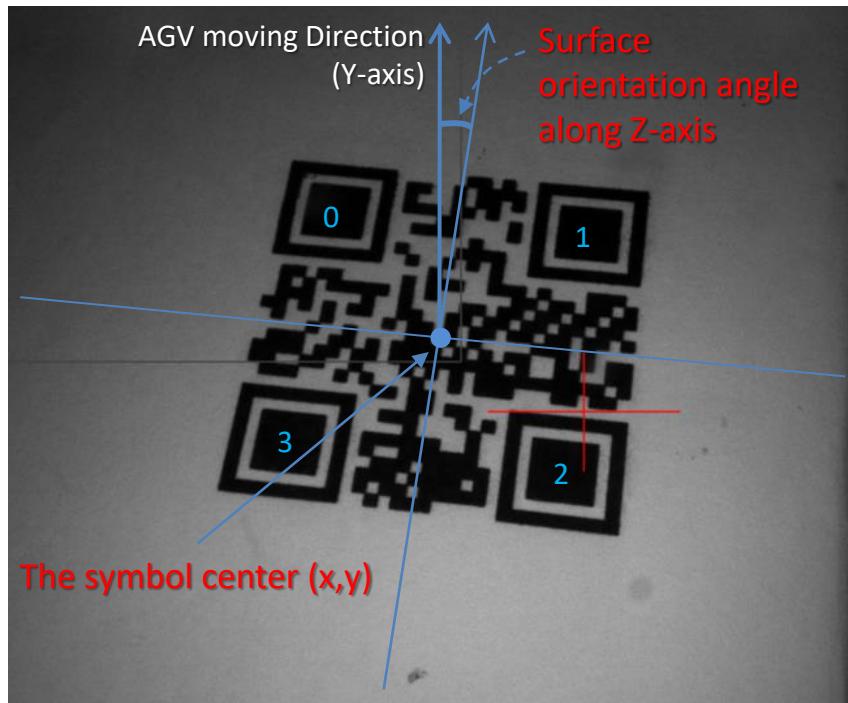
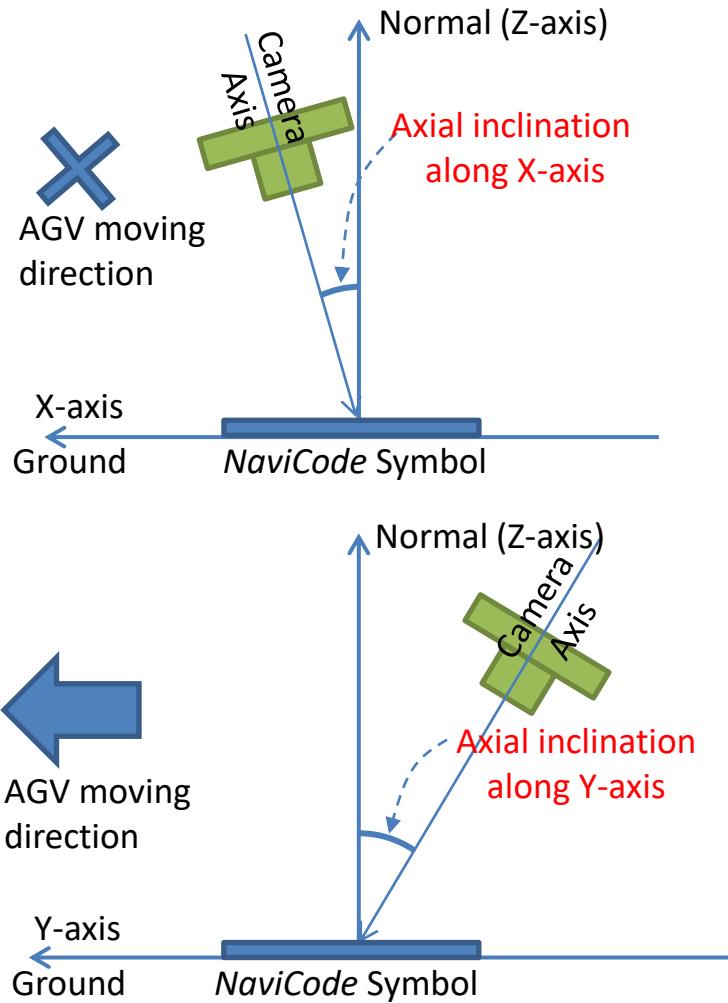
QR decodable worse-case

# Comparisons among common 2D codes, Amazon Code and NaviCode for Navigation

	Amazon AGV code	QR Code (v. 3)	Data Matrix (32x32)	NaviCode
Symbologies				
Data contents	3.5 bytes 	70 bytes   	60 bytes   	44 bytes  
ECC capability & data security	0% 	30%   	30%   	46%   
Easy to locate	 	  	 	  
Reading speed	  	  	 	  
Intrinsic precision for navigation info	 	  	 	  

# Appendix A

## Gesture Info – 3 Angles & a Reference Point



# Evaluation kit – MIR8N

**Dimension (mm) :** 52 W x 66 L x 21.2 H

**Field of view:** 80° x 57° (W x L)

**Illumination:** white light LED x 6

**Output Interface:** 1.5m USB , VCOM or UART

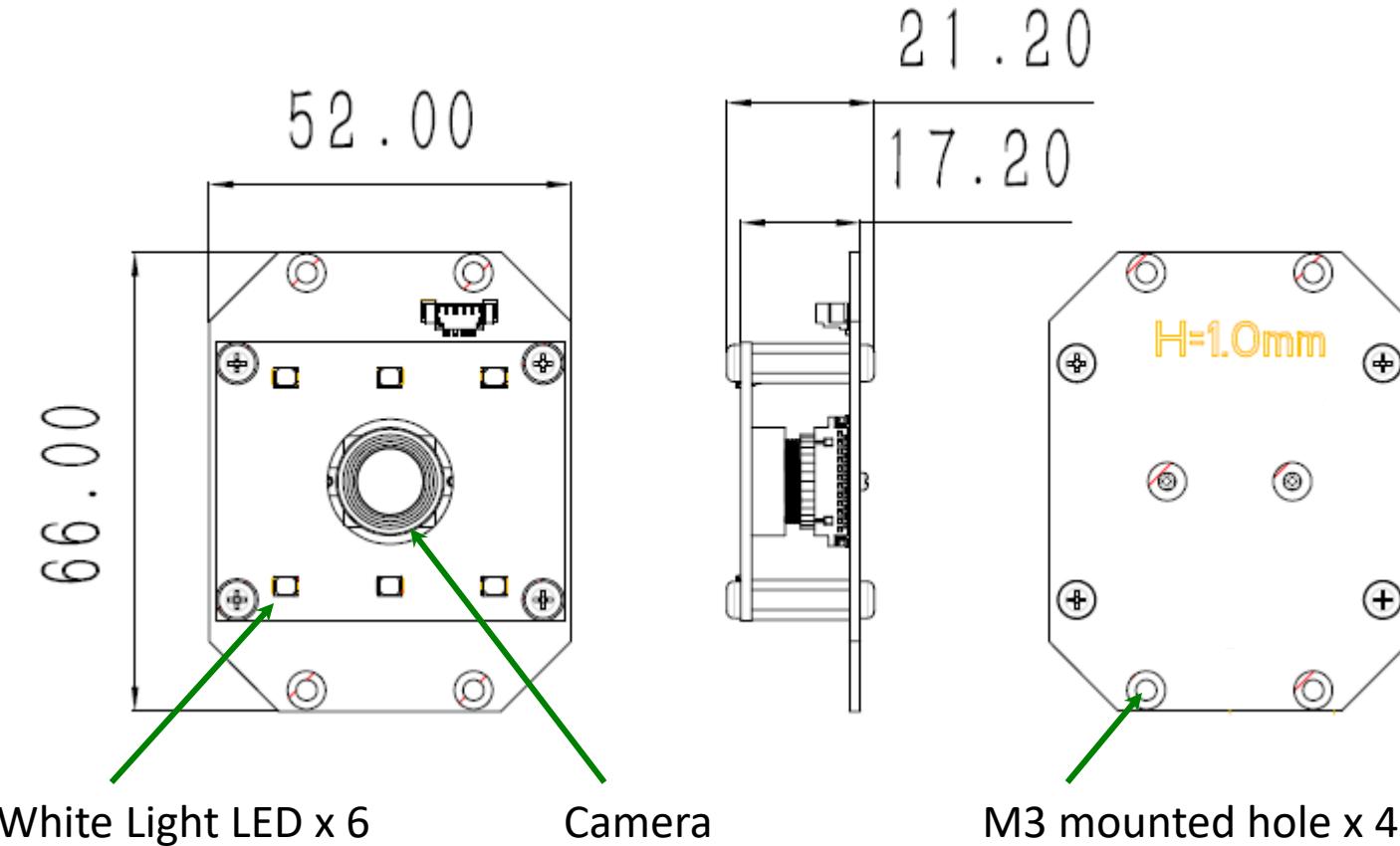
**Power:** 5V/0.5A

Command **SDK** and document



# Evaluation kit – MIR8N

Dimension: mm



# Evaluation kit – MIR8N

**Field of view:**  $80^\circ \times 57^\circ$  (W x L)

